

"WS10 Connected Vehicles and Cooperative Systems" Programme

Lanzarote	ID	Title	Corresponding Author	
1340-1355	Opening			
1355-1405	1472	Vehicle-infrastructure localization based on the SME filter	Feihu	Zhang
1405-1420				
1420-1430	1479	Merging Driver Assistance Decision System Using Occupancy Grid-based Traffic Situation Representation	Kenan	Mu
1430-1445				
1445-1455	1485	An automatic calibration system of vehicle motion error under GPS blind area	Jingmei	Zhou
1455-1510				
1510-1530	Break			
1530-1540	1481	Multi-Resolution-Modeling for Testing and Evaluation of VANET applications	Manuel	Schiller
1540-1555				
1555-1605	1505	An Intersection Game-Theory-Based Traffic Control Algorithm in a Connected Vehicle Environment	Hesham	Rakha
1605-1620				
1620-1630	1531	An integral approach to autonomous and cooperative vehicles development and testing	Igor	Passchier
1630-1645				